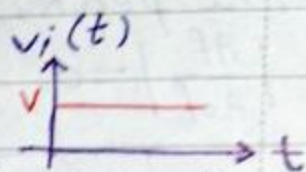


4.5 Step Response



$$v_i(t) = V \rightarrow v_i(s) = V/s$$

$$\frac{V_o(s)}{V_i(s)} = \frac{V_o(s)}{V/s} = \frac{A_0 f}{(s/\omega_0)^2 + 2K(s/\omega_0) + 1}$$

$$\therefore \frac{V_o(s)}{A_0 f V} = \frac{1}{s \left[(s/\omega_0)^2 + 2K(s/\omega_0) + 1 \right]}$$

$$\therefore s_{1,2f} = -K\omega_0 \pm \omega_0 \sqrt{K^2 - 1}$$

(a) if $K=1$ then the Two poles are coincide to critically damping case

$$\therefore \frac{V_o(t)}{VA_0 f} = 1 - (1 + \omega_0 t) e^{-\omega_0 t} \quad \text{the response}$$

(b) If $K < 1$, the two poles are complex conjugate corresponding to underdamping case.

Where the response is a sinusoid with amplitude decays with time.

$$s_{1,2f} = -\omega_0 K \pm j\omega_0 \sqrt{1 - K^2}$$

wd \Rightarrow damping freqy $= \omega_0 \sqrt{1 - K^2}$

$$\frac{V_o(t)}{V_{Aof}} = 1 - \underbrace{\left(K \frac{\omega_o}{\omega_d} \sin \omega_d t + \cos \omega_d t \right)}_{\text{oscillation}} e^{-K \omega_o t}$$

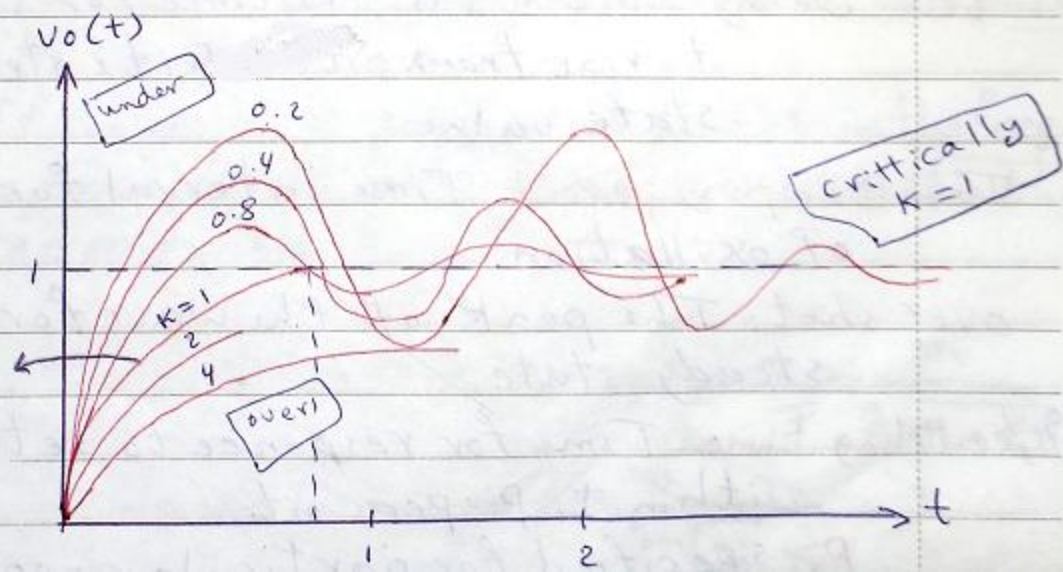
© If $K > 1$, Both poles are real and (-ve) which corresponding to overdamped case where the response approaches its final steady state value after a time without oscillation.

$$\frac{V_o(t)}{V_{Aof}} = 1 - \frac{1}{2\sqrt{K^2-1}} \left(\frac{1}{K_1} e^{-K_1 \omega_o t} - \frac{1}{K_2} e^{-K_2 \omega_o t} \right)$$

Where $s_1 f = -\omega_o K_2$, $s_2 f = -\omega_o K_1$

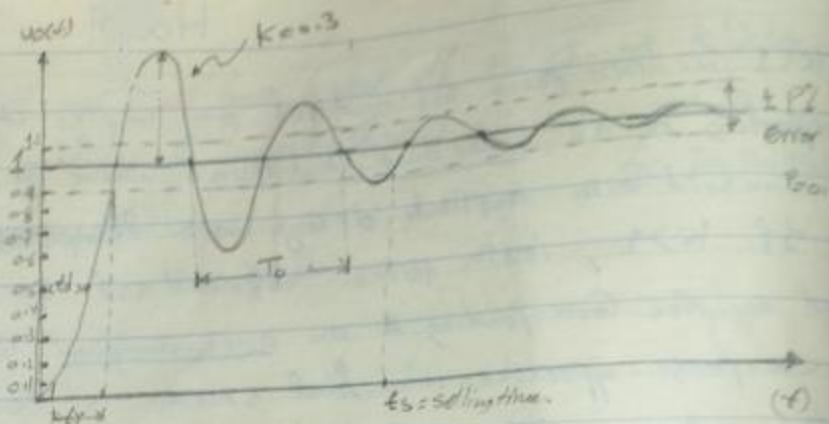
$$K_1 = K - \sqrt{K^2-1}, \quad K_2 = K + \sqrt{K^2-1}$$

if $4K^2 \gg 1$ then $V_o(t)/V_{Aof} = 1 - e^{-\omega_o t/2K}$



$$V = 1 \text{ volt}$$

$$A_{of} = 1$$



Step response of Two pole f.B. ampf. for a damping factor $K = 0.3$

tr: Rise time: time for the waveform to rise from 0.1 to 0.9 of its steady state value.

td: Time for the waveform to rise from 0 to 0.5 of its steady state value.

Damp Period (T_o): Time interval for 1 cycle of oscillations

Over shoot: Peak excursion above the steady state value.

Settling time: Time for response to settle to within $\pm 1\%$ percent.

P: Specified ~~input~~ for a particular application.

Unit Step Response.

$$y = v_{out} / v_{Aof}$$

$$x = t/T_o \quad T_o = 2\pi/\omega_o \text{ under damp Period.}$$

The max. of y are obtained at $x = x_m$

$$x_m = \omega_o t_m / 2\pi = m / 2(1-K^2)^{1/2}$$

$$y_m = \frac{v_o(t_m)}{v_{Aof}} = 1 - (-1)^m e^{-\pi K x_m}$$

$$\text{overshoot} = e^{-2\pi K x_m}$$

where m is integer.

* $y = V_o(t)/V_{A0}$ of take $x = t/T_0$ & $T_0 = 2\pi/\omega_0$
→ underdamping period

* The max of $y \rightarrow x = x_{max} \rightarrow x_m = \omega_0 t_m / 2\pi$

$$\therefore x_m = \frac{m}{2\sqrt{1-K}}$$

$$y_m = 1 - (-1)^m e^{-2\pi K x_m}$$

$$\text{overshoot} = e^{-2\pi K x_m}$$

* The max. occurs for all odd value of m .

* The min. occurs for all even value of m .

Ex. (a) If $K = 0.5$, Calculate the percent max. overshoot in the step response for two pole F.B. amp.

(b) If there is 10 percent overshoot in the frequency response, what is the percent overshoot in the step response.

Ans. @ The max. occurs at $m=1$

$$y = x_1 = \frac{1}{2} \sqrt{1 - K^2} = 0.5773$$

$$\text{max overshoot} = e^{-2\pi K x_1} = 0.163 = 16.3\%$$

⑥ In freqy response, the max overshoot = $\frac{1}{2K\sqrt{1-K^2}}$
 $-1 = 0.1$

$$K^2(1-K^2) = 0.2066$$

$$\therefore K^2 - K^4 - 0.2066 = 0$$

$$\therefore K^2 = \frac{1}{2} \pm \frac{\sqrt{1 - 4 \times 0.2066}}{2} = 0.5 \pm 0.208$$

$$\textcircled{1} K^2 = 0.708 \Rightarrow K = 0.8416$$

$$\therefore x_1 = \frac{1}{2} \sqrt{1 - K^2} = 0.925$$

$$\text{max overshoot} = e^{-2\pi K x_1} = 0.747\%$$

$$\textcircled{2} K^2 = 0.292 \Rightarrow K = 0.54 \Rightarrow x_1 = 0.594$$

$$\therefore \text{max overshoot} = e^{-2\pi K x_1} = 13.32\%$$

\therefore The max. overshoot in the step response corresponding to $K = 0.54$ is 13.32%

Ex 2/ Given Two Pole damp. with $\omega_1 = 1 \text{ rad/sec}$, $\omega_2 = 0.2 \text{ rad/sec}$

a) Find the max value of the loop gain for which the step response

- b) At What time will the peak occur. {the time at which occur}
- c) calculate the magnitude of the first min. of the step response at
- d) Verify That for $K = 0.707$, the max. overshoot is 4.3 Percent.

Ans:- a) The max. occur at $m=1$ & overshoot $= e^{-\pi \zeta m / \sqrt{1-\zeta^2}}$, So

$$0.1 = e^{-\pi \zeta / \sqrt{1-\zeta^2}} \Rightarrow 2.3 = \frac{\pi \zeta}{\sqrt{1-\zeta^2}} \Rightarrow 0.537 = \frac{\zeta^2}{1-\zeta^2} \Rightarrow$$

$$\Rightarrow \zeta^2 = 0.349 \rightarrow \therefore \zeta = 0.541$$

$$\phi = 1/2 \pi = 0.845, \omega_0 = \phi (\omega_1 + \omega_2) = 1.014 \text{ M rad/sec.}$$

$$\omega_0 = \sqrt{\omega_1 \omega_2 (1 + \beta A_0)} \Rightarrow \beta A_0 = \frac{\omega_0^2}{\omega_1 \omega_2} - 1 = 4.14$$

b) $\frac{t_m \omega_0}{2\pi} = \frac{m}{2\sqrt{1-\zeta^2}}$ & The Peak occur at $m=1$

$$t_{\text{peak}} = \frac{\pi}{\omega_0 \sqrt{1-\zeta^2}} = \frac{\pi}{1.014 \times 10^6 \sqrt{1-0.541^2}} = 3.84 \text{ M Sec.}$$

c) $y_2 = 1 - e^{-2\pi \zeta m}$, first min occur at $m=2$

$$x_2 = \frac{2}{\sqrt{1-\zeta^2}} = 1.24 \Rightarrow y_2 = 0.98999$$

$$\frac{t_2 \omega_0}{2\pi} = \frac{2}{2\sqrt{1-\zeta^2}} \Rightarrow t_{2\text{peak}} = \frac{2\pi}{\omega_0 \sqrt{1-\zeta^2}} = 7.68 \text{ M sec}$$

d) $m=1, x_1 = 1/2 \sqrt{1-\zeta^2} = 1/2 \sqrt{1-0.707^2} = 0.707$

$$\text{Overshoot} = e^{-2\pi \zeta x_1} = 0.043 = 4.3\%$$